

Investigating oscillation techniques during collaborative robot-assisted wire arc additive manufacturing



Jackson Motley, Mohammad Arjomandi, Tuhin Mukherjee
Department of Mechanical Engineering, Iowa State University

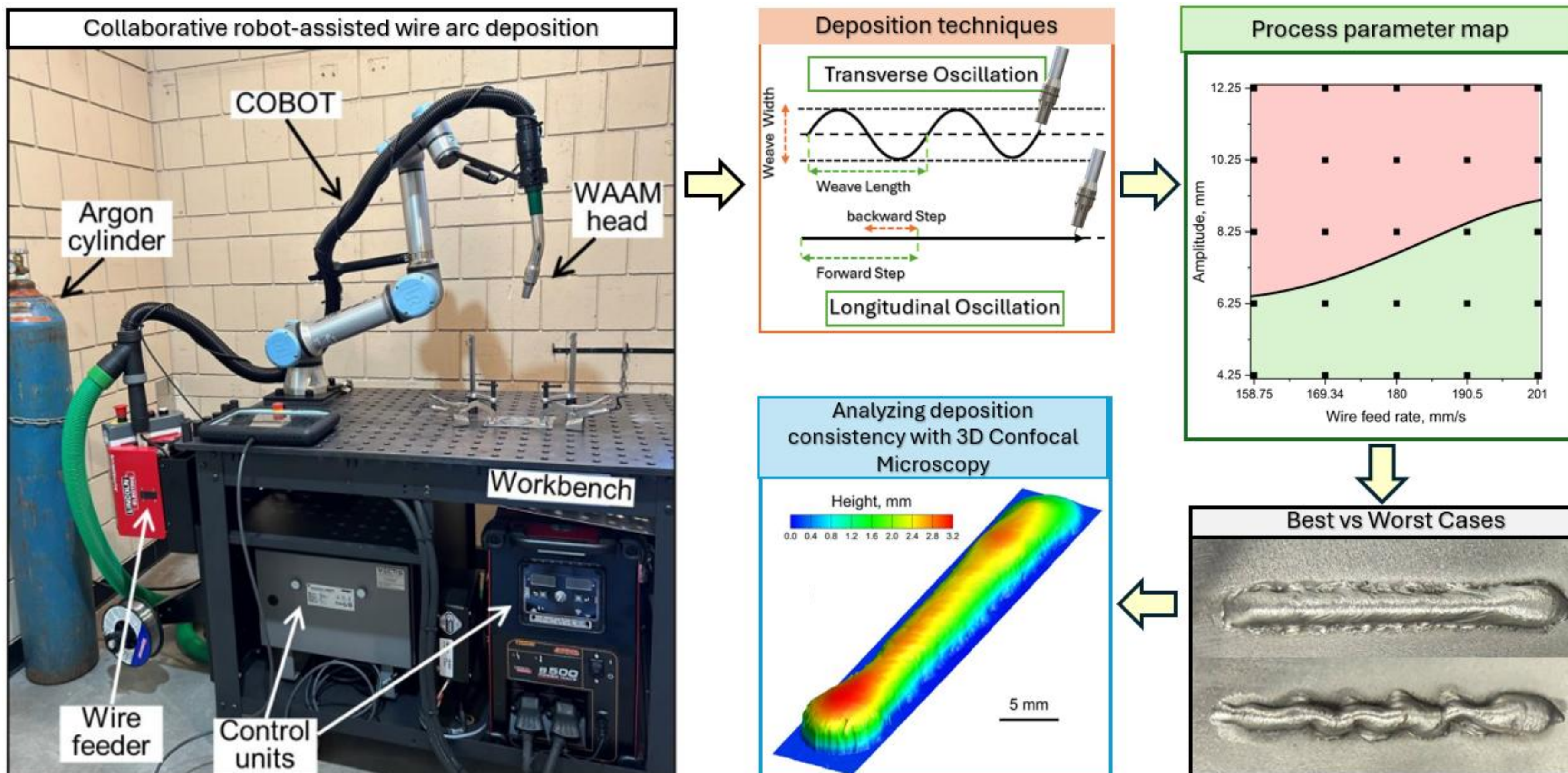


Figure 1: A schematic representation of the methodology used in this work.

Problem Statement and Objective

- This work utilizes oscillation techniques to enhance the deposition quality through collaborative robotics in the wire arc additive manufacturing (WAAM) process.
- The purpose of this study is to assess how various process parameters influence track integrity when oscillation techniques are employed to increase the productivity and viability of WAAM.

Methods

- Two cases were developed to study oscillations impact on deposition quality and defect formation: (a) benchmark deposition, (b) increased travel speed.
- A qualitative process map was generated for the analysis of amplitude in comparison with:
 - Frequency of transverse oscillation.
 - Process parameters during longitudinal oscillation.
- Two cases were identified to highlight oscillations in mitigating defect formation: (c) transverse oscillation, and (d) longitudinal oscillation.
- Cases (a)-(d) were analyzed through confocal microscopy and validated computationally.

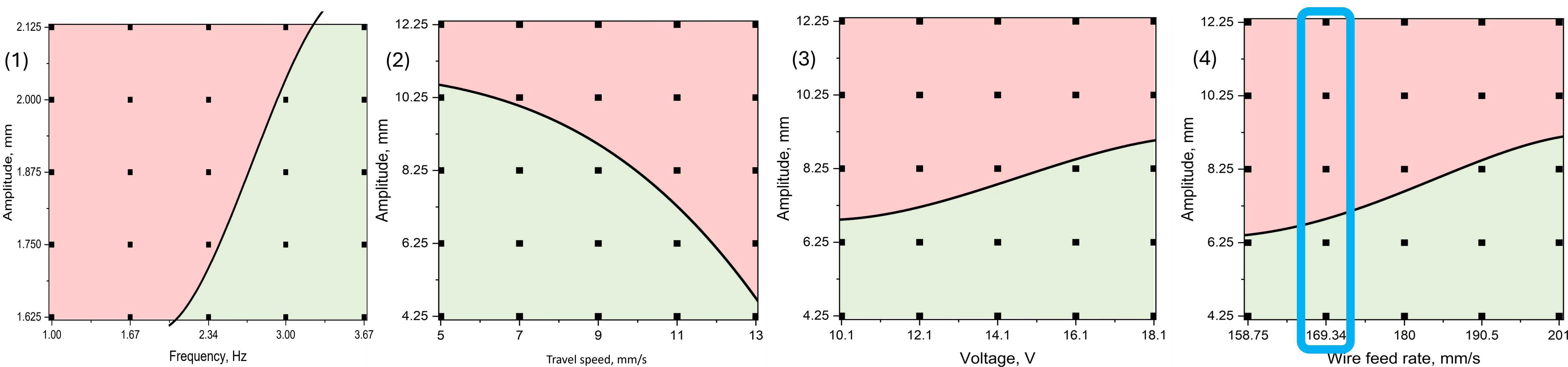


Figure 2: Graphs representing 25 tracks for comparison of humping formation. Graphs 1 represents transverse oscillation, while graphs 2-4 longitudinal.

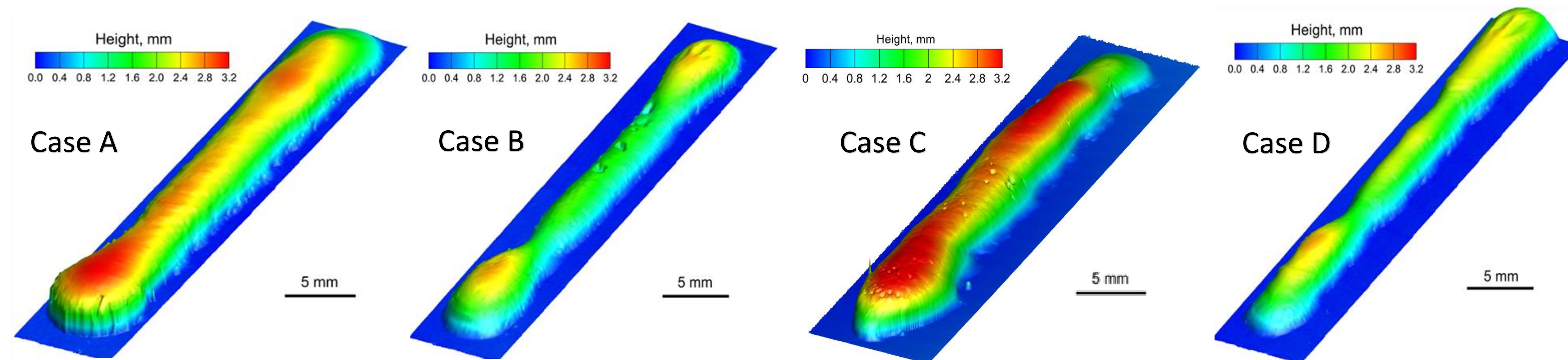


Figure 4: Height maps of different depositions for comparison between non-oscillatory and oscillatory movement, generated using confocal microscopy.

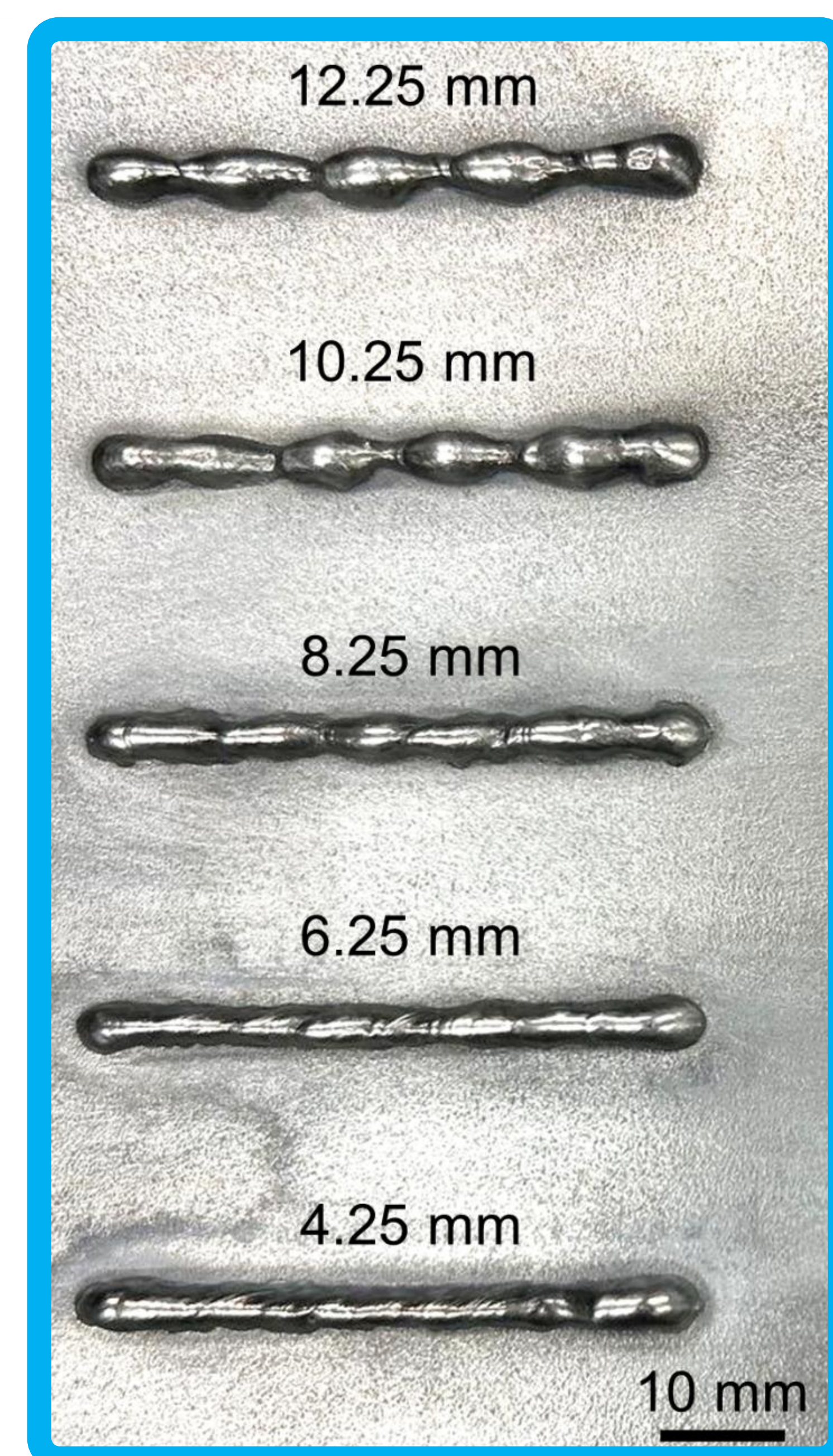


Figure 3: A demonstration of amplitudes affect on track integrity quantification for a wire feed rate of 169.34 mm/s.

Frequency Calculations

Here, *Length* is the linear distance traveled by the weld head during one cycle. For Longitudinal Oscillation, this is the sum of the Forward and Back step distances. For Transverse Oscillation, *Length* is equivalent to the wavelength.

$$\text{Frequency} = \frac{\text{Travel Speed}}{\text{Length}}$$

Track Integrity

Here, *N* denotes the total number of height measurements taken along the length, *Z* is the deposited track's height at the track's mid-width, and *Z_m* is the mean height. Therefore, the height deviation indices indicate the deviation of track height from the mean height along the track.

$$h_A = \frac{\sum_N |Z - Z_m|}{N} \quad h_{RMS} = \sqrt{\frac{\sum_N (Z - Z_m)^2}{N}}$$

Discussion

- Specific waveform parameters- such as oscillation direction- influence bead formation at varying travel speeds.
- Increased track width can be strategically leveraged to reduce overall build time in multi-track deposition processes.

Conclusions

- Longitudinal oscillation was found to enhance track integrity, especially at high travel speeds.
- Transverse oscillation increased the width of the track, suggesting improved deposition productivity.

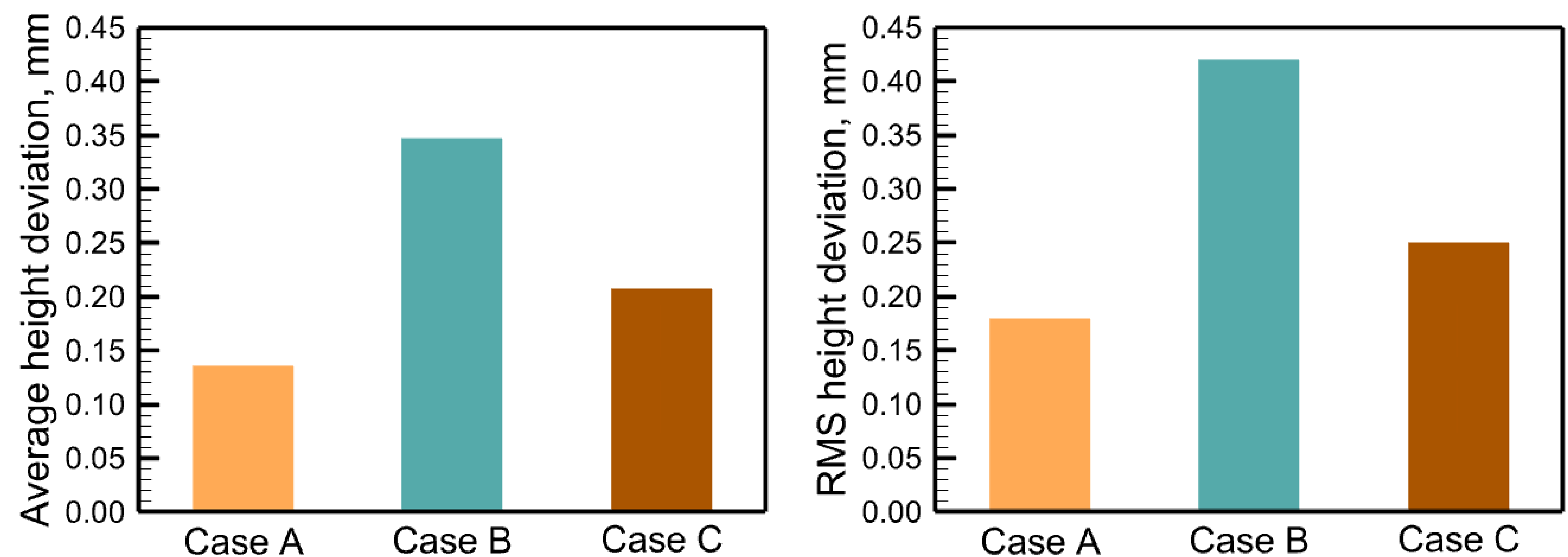


Figure 5: Graphs showcasing average height deviation and RMS, which support increased deposition integrity

Results

- Observations of **longitudinal oscillation** and its effect on track integrity showed improved deposition quality when compared to tracks with no oscillatory movement at similar travel speeds.
- Observations of **transverse oscillation** and its effect on track integrity showed enhanced productivity while maintaining weld quality found in non-oscillatory welds at same travel speeds.

Acknowledgments

- We sincerely acknowledge Curtis Mosher, of the Carver Lab at Iowa State University, and support from the Honors Program at Iowa State University. Research was supported by the Iowa State University faculty start-up fund.